

# Design of Cognitive Radio Systems Under Temperature-Interference Constraints: A Variational Inequality Approach

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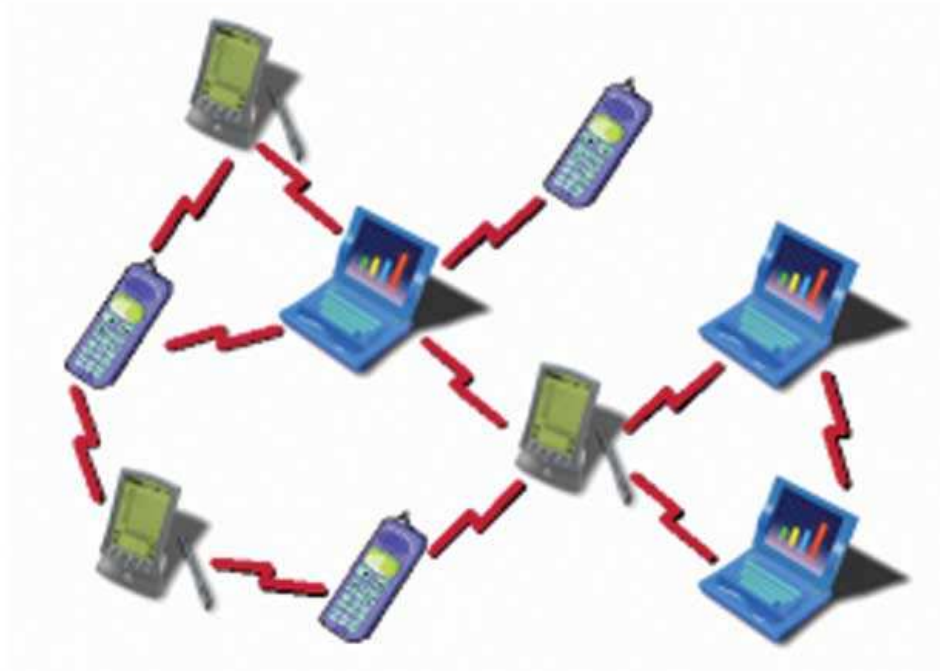
# Outline of the Talk

- Games in Ad-Hoc Networks
  - the waterfilling operator and the iterative waterfilling algorithm
- Games in Cognitive Radio Systems
  - Individual temperature-interference constraints
  - Global temperature-interference constraints
- Variational Inequality Theory
- Numerical results
- Summary

# Games in Ad-Hoc Networks

# Competitive Ad-Hoc Networks

- Consider a decentralized and competitive network of users fighting for the resources (i.e., spectrum):



- Game theory is a very adequate mathematical framework to analyze such systems and design effective strategies.

# Signal Model for Ad-Hoc Networks

- Signal received by link  $q$ , for carriers  $k = 1, \dots, N$ :

$$y_{qq}(k) = H_{qq}(k) x_q(k) + \sum_{r \neq q} H_{qr}(k) x_r(k) + w_q(k).$$

- The optimization variables correspond to the power allocation over the carriers:  $\mathbf{p}_q = \{p_q(k)\}_{k=1}^N$ .
- There is a power budget for each user:

$$\sum_{k=1}^N p_q(k) \leq P_q.$$

- The payoff for user  $q$  is the transmission rate:

$$R_q(\mathbf{p}_q, \mathbf{p}_{-q}) = \sum_{k=1}^N \log(1 + \text{sinr}_q(k))$$

where

$$\text{sinr}_q(k) = \frac{|H_{qq}(k)|^2 p_q(k)}{1 + \sum_{r \neq q} |H_{rq}(k)|^2 p_r(k)}.$$

- The feasible set for the variables is

$$\mathcal{P}_q = \left\{ \mathbf{p}_q \in \mathbb{R}_+^N : \sum_{k=1}^N p_q(k) = P_q \right\}.$$

# Game Formulation for Ad-Hoc Networks

- Each of the  $Q$  users selfishly maximizes its own rate subject to the constraints:

$$\begin{array}{ll} \underset{\mathbf{p}_q}{\text{maximize}} & \sum_{k=1}^N \log(1 + \text{sinr}_q(k)) \\ \text{subject to} & \mathbf{p}_q \in \mathcal{P}_q \end{array} \quad q = 1, \dots, Q.$$

- The best response for each user has a nice and simple closed-form expression:

$$\mathbf{p}_q^* = \text{wf}_q(\mathbf{p}_{-q})$$

where  $\text{wf}_q(\mathbf{p}_{-q}) \triangleq (\mu_q - \mathbf{interf}_q)^+$  is the waterfilling operator.

- Different researchers have actively worked on this problem since 2001 [Yu-Ginis-Cioffi'01].



- The Nash Equilibrium (NE) is a simultaneous waterfilling for all users:

$$\mathbf{p}_q^* = \text{wf}_q(\mathbf{p}_{-q}^*) \quad q = 1, \dots, Q.$$

- Convex game  $\Rightarrow$  the existence of a NE follows readily.
- We can devise different iterative algorithms based on the waterfilling best response.
- New interpretation of waterfilling as a projection [ScuPalBar'06]:  
 $\mathbf{p}_q = [-\mathbf{interf}_q]_{\mathcal{P}_q}$ .
- With this new interpretation, it is simple to show uniqueness of NE and prove convergence of iterative waterfilling algorithms (IWFA).

# Asynchronous IWFA

- Users update the power allocation in a totally asynchronous way based on  $\text{wf}_q(\cdot)$ :
  - users may update at arbitrary and different times and more or less frequently than others
  - users may use an outdated measure of interference
- **Theorem [ScuPalBar'06]:** The asynchronous IWFA converges to the unique NE if  $\rho(\mathbf{H}^{\max}) < 1$ , where

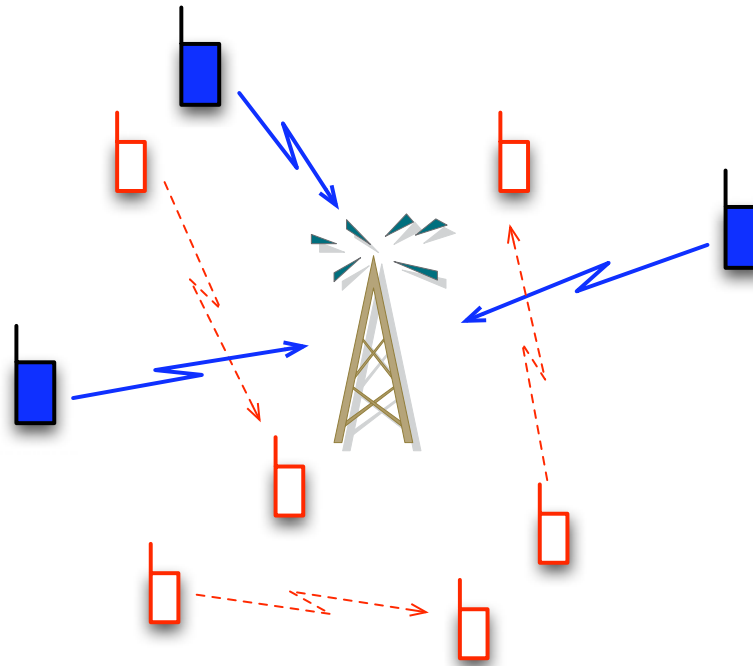
$$[\mathbf{H}^{\max}]_{qr} \triangleq \begin{cases} \max_{k \in \mathcal{D}_r \cap \mathcal{D}_q} \left\{ \frac{|H_{rq}(k)|^2}{|H_{qq}(k)|^2} \right\} & \text{if } q \neq r \\ 0 & \text{otherwise.} \end{cases}$$

and  $\mathcal{D}_q = \{1, \dots, N\} - \{\text{bad subcarriers}\}$ .

# Games in Cognitive Radio (CR) Systems

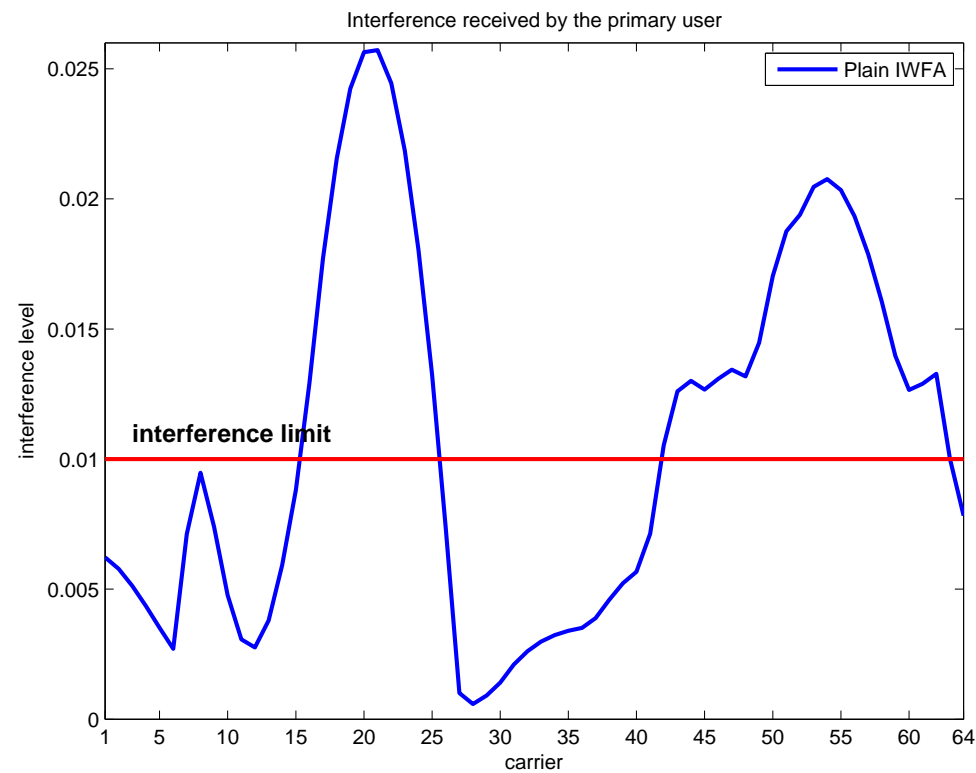
# CR Systems

- Consider now an established network of primary users on top of which some secondary users play the previous game.



- Hierarchical CR networks
  - PU=Primary users (legacy spectrum holders)
  - SU=Secondary users (unlicensed users)

- Opportunistic communications: SUs can use the spectrum subject to not inducing too much interference on the PUs.
- The previous iterative waterfilling algorithm does not work because it violates the interference constraint:



# Signal Model for CR Systems

- Same signal model as for ad-hoc networks with the additional temperature-interference constraints:

$$|G_{qp}(k)|^2 p_q(k) \leq \alpha_p$$

where  $|G_{qp}(k)|^2$  is the cross-channel gain between the  $q$ th secondary and the  $p$ th primary user and  $\alpha_p$  is the maximum level of interference tolerable by the primary user from each secondary user.

- Equivalently, we can write these constraints as

$$p_q(k) \leq p_q^{\max}(k) \quad \forall k, q.$$

# Game Formulation for Ad-Hoc Networks

- Each of the  $Q$  users selfishly maximizes its own rate subject to the constraints:

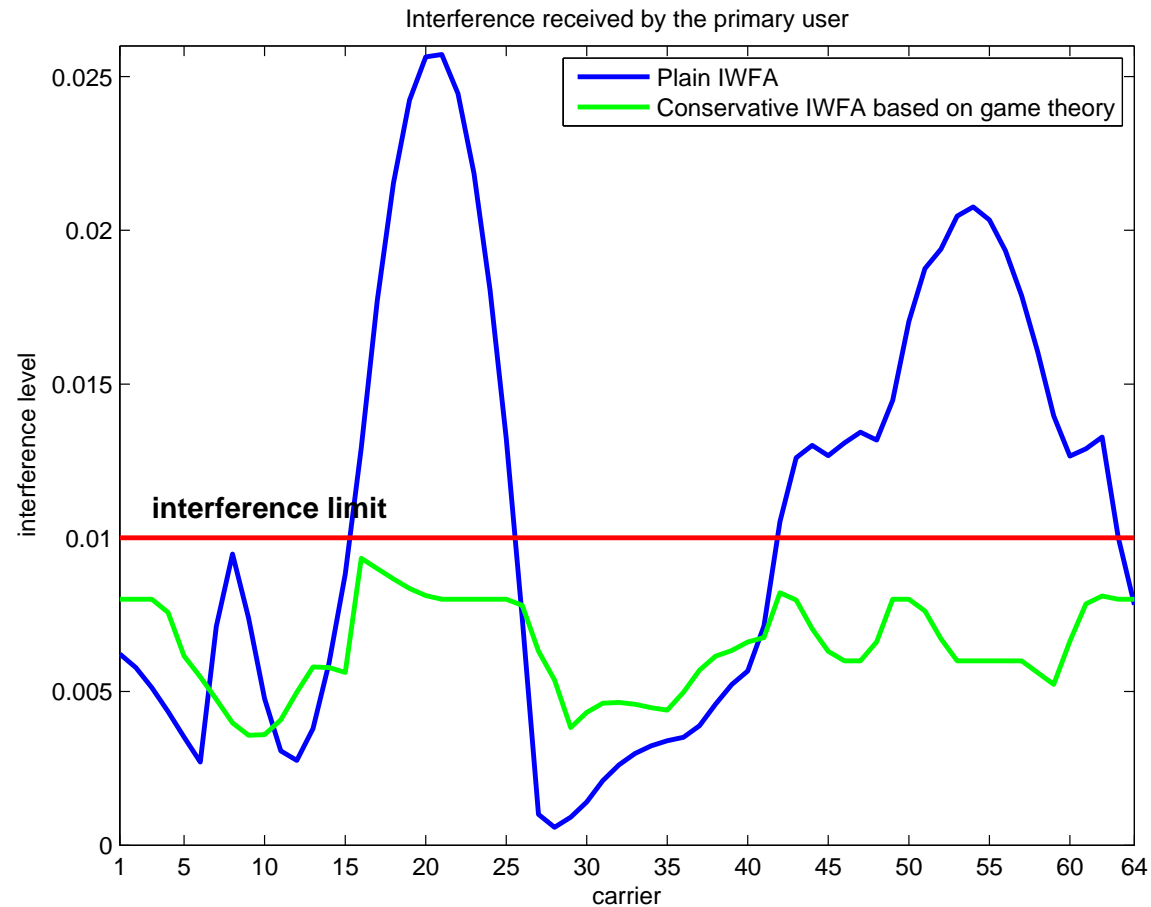
$$\begin{aligned} & \underset{\mathbf{p}_q}{\text{maximize}} && \sum_{k=1}^N \log(1 + \text{sinr}_q(k)) \\ & \text{subject to} && \sum_{k=1}^N p_q(k) \leq P_q && \forall q = 1, \dots, Q. \\ & && 0 \leq p_q(k) \leq p_q^{\max}(k), && \forall k \end{aligned}$$

- The best response in this case also has a nice and simple closed-form expression based on a modified waterfilling with clipping from above:

$$\widetilde{\text{wf}}_q(\mathbf{p}_{-q}) \triangleq [\mu_q - \mathbf{interf}_q]_0^{\mathbf{p}^{\max}}.$$

- The analysis of this game and the algorithms are similar to the previous one.

- However, this method may be too conservative as the level of interference from each secondary user is limited individually in a conservative way:





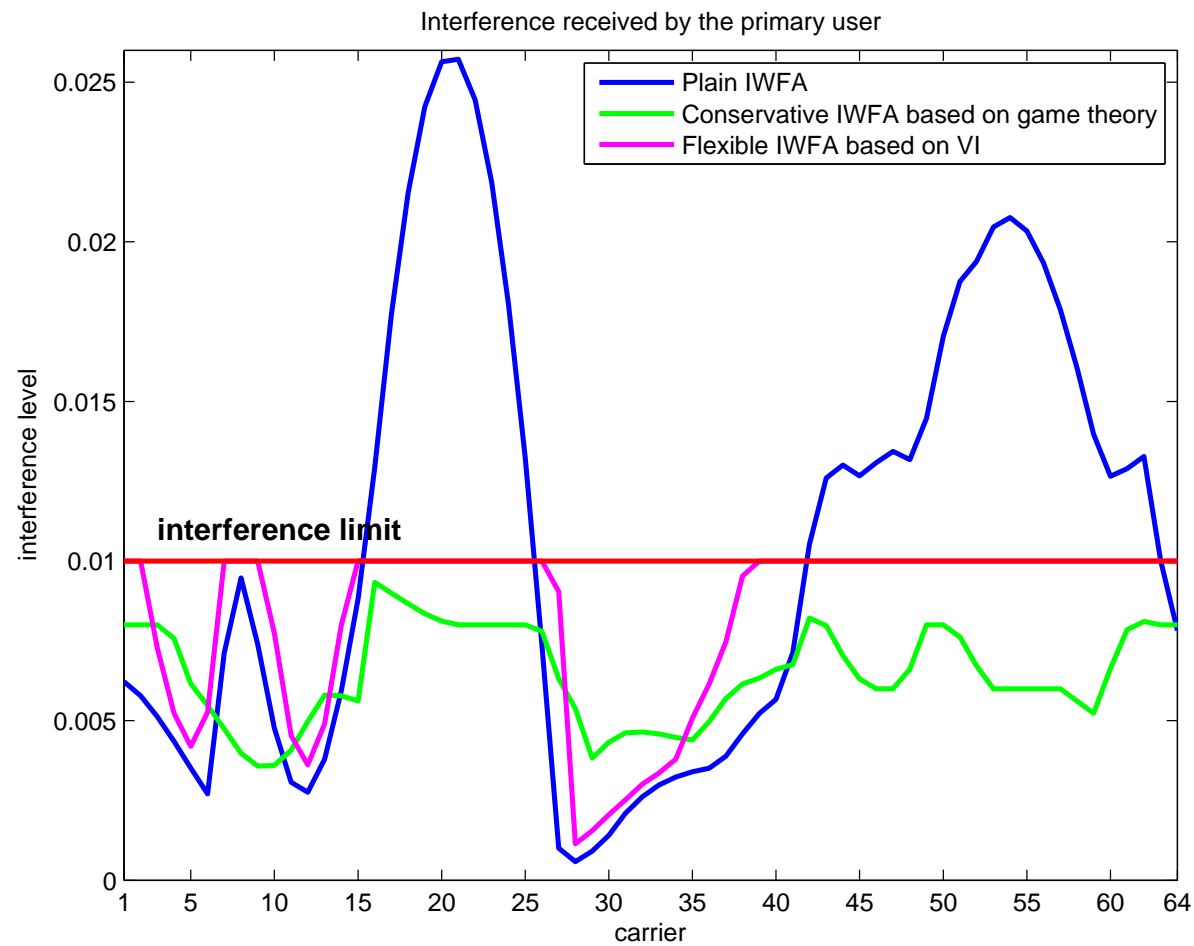
# Revised Signal Model for CR Systems

- The really important quantity is not the individual interference generated by each secondary user but the aggregate interference generated by all of them.
- We can then limit the aggregate interference instead:

$$\sum_{q=1}^Q |G_{qp}(k)|^2 p_q(k) \leq \alpha_p.$$

- This will achieve our goal without being conservative or accidentally violating the limit.

- Indeed, this new reformulation achieves our goal in a remarkable way:



- The price to pay for including the coupling constraints is twofold:
  - on a mathematical level, it complicates the analysis of the game and its design
  - on the practical side, this new game must include some mechanism to calculate the aggregate interference.
- For the practical aspect, one approach is to allow the primary users to estimate the aggregate interference and then broadcast a minimum of signaling. But this only makes sense if the signaling is really minimum and scales nicely.
- For the mathematical analysis and design, we need more advance tools: **variational inequality theory**.

# Variational Inequality (VI) Theory

# The Variational Inequality Problem

- Given a closed and convex set  $\mathcal{K} \subseteq \mathbb{R}^n$  and a mapping  $\mathbf{F} : \mathcal{K} \rightarrow \mathbb{R}^n$ , the VI problem  $\text{VI}(\mathcal{K}, \mathbf{F})$  is to find a vector  $\mathbf{x}^* \in \mathcal{K}$  such that

$$(\mathbf{y} - \mathbf{x}^*)^T \mathbf{F}(\mathbf{x}^*) \geq 0 \quad \forall \mathbf{y} \in \mathcal{K}.$$

- The  $\text{VI}(\mathcal{K}, \mathbf{F})$  reduces to the minimum principle (convex optimization problems) if  $\mathbf{F} = \nabla f$

$$\text{VI}(\mathcal{K}, \nabla f) \iff \min_{\mathbf{x} \in \mathcal{K}} f(\mathbf{x})$$

- The  $\text{VI}(\mathcal{K}, \mathbf{F})$  encompasses a wider range of problems than classical optimization whenever  $\mathbf{F} \neq \nabla f$  ( $\Leftrightarrow \mathbf{F}$  has not a symmetric Jacobian).

- Other classical problems that fall in the VI framework:

- *System of equations*:  $\mathcal{K} = \mathbb{R}^n \Rightarrow \text{VI}(\mathcal{K}, \mathbf{F}) \Leftrightarrow \mathbf{F}(\mathbf{x}) = \mathbf{0}$

- *Nonlinear complementarity problem (NCP)*:  $\mathcal{K} = \mathbb{R}_+^n \Rightarrow \text{VI}(\mathcal{K}, \mathbf{F}) \Leftrightarrow \text{NCP}(\mathbf{F})$

$$\text{NCP}(\mathbf{F}) : \quad \mathbf{0} \leq \mathbf{x}^* \perp \mathbf{F}(\mathbf{x}^*) \geq \mathbf{0}$$

(The NCP is a unifying mathematical framework for linear programming, quadratic programming, and bi-matrix games.)

- *Fixed-point problems*:  $\mathbf{F} = \mathbf{x} - \mathbf{G}(x) \Rightarrow \text{VI}(\mathcal{K}, \mathbf{F}) \Leftrightarrow \mathcal{K} \ni \mathbf{x} = \mathbf{G}(\mathbf{x})$

- *Nash equilibrium problems (NEP)*:  $\mathcal{K} = \prod_q \mathcal{K}_q$  and  $\mathbf{F}(\mathbf{x}) = (\mathbf{F}_q(\mathbf{x}))_{q=1}^Q$  with  $\mathbf{F}_q = \nabla_{\mathbf{x}_q} f_q(\mathbf{x}_q, \mathbf{x}_{-q}) \Rightarrow$

$$\text{VI}(\mathcal{K}, \mathbf{F}) \iff \min_{\mathbf{x}_q \in \mathcal{K}_q} f_q(\mathbf{x}_q, \mathbf{x}_{-q}), \quad \forall q = 1, \dots, Q.$$

# Formulation of the Game with Coupling Constraint

- Recall the game formulation with the coupling constraint:

$$\mathcal{G} : \begin{array}{ll} \text{maximize} & \sum_{k=1}^N \log(1 + \text{sinr}_q(k)) \\ \mathbf{p}_q \geq \mathbf{0} & \\ \text{subject to} & \sum_{k=1}^N p_q(k) \leq P_q \end{array} \quad \forall q = 1, \dots, Q$$

$$\sum_{q=1}^Q |G_{qp}(k)|^2 p_q(k) \leq \alpha_p \quad \forall p = 1, \dots, P.$$

- This is a GNEP with a common constraint.
- It can be “rewritten” as a VI problem (caveat: only the variational solutions with common multipliers are considered).

# Formulation of the Game with Coupling Constraint via Pricing

- To deal with coupling interference constraints while keeping the optimization as decentralized as possible we introduce pricing:

$$\mathcal{G}_\lambda : \begin{array}{ll} \underset{\mathbf{p}_q \geq 0}{\text{maximize}} & r_q(\mathbf{p}_q, \mathbf{p}_{-q}) - \sum_{p=1}^P \sum_{k=1}^N \lambda_{p,k} |G_{qp}(k)|^2 p_q(k) \\ \text{subject to} & \sum_{k=1}^N p_q(k) \leq P_q \end{array} \quad \forall q$$

where the prices  $\lambda_{p,k} \geq 0$  are chosen such that

$$\text{(CC)} : \quad 0 \leq \lambda_{p,k} \quad \perp \quad \alpha_{p,k} - \sum_{q=1}^Q |G_{qp}(k)|^2 p_q(k) \geq 0 \quad \forall p, \quad \forall k$$

- We will now rewrite the game  $\mathcal{G} \triangleq \mathcal{G}_\lambda \cup \text{(CC)}$  as a VI problem.



- **Theorem 1 (Game as a VI):** *The game  $\mathcal{G}$  is equivalent to the VI( $\mathcal{K}, \mathbf{F}$ ) where*

$$\mathcal{K} \triangleq \left\{ \mathbf{p} \in \mathbb{R}_+^{NQ} : \sum_{k=1}^N p_q(k) \leq P_q \text{ and } \sum_{q=1}^Q |G_{qp}(k)|^2 p_q(k) \leq \alpha_{p,k}, \forall q, p, k \right\}$$

and

$$\mathbf{F}(\mathbf{p}) \triangleq \begin{pmatrix} -\nabla_{\mathbf{p}_1} r_1(\mathbf{p}) \\ \vdots \\ -\nabla_{\mathbf{p}_Q} r_Q(\mathbf{p}) \end{pmatrix}.$$

- The equivalence is in *the following sense:*
  - If  $\mathbf{p}^{\text{VI}}$  is a solution of the VI, then there exist multipliers  $\boldsymbol{\lambda}^{\text{VI}}$  such that  $(\mathbf{p}^{\text{VI}}, \boldsymbol{\lambda}^{\text{VI}})$  is an equilibrium pair of  $\mathcal{G}$
  - Conversely, if  $(\mathbf{p}^{\text{NE}}, \boldsymbol{\lambda}^{\text{NE}})$  is an equilibrium pair of  $\mathcal{G}$ , then  $\mathbf{p}^{\text{NE}}$  is a solution of the VI, and  $\boldsymbol{\lambda}^{\text{NE}}$  are multipliers of the VI.

# Results from the VI Framework: Solution Analysis

- Using the VI framework we can study existence/uniqueness of the solution and devising distributed algorithms.
- Let's introduce now the interference violation function  $\Phi(\boldsymbol{\lambda})$  :  
 $\mathbb{R}_+^{PN} \ni \boldsymbol{\lambda} \mapsto \mathbb{R}^{PN}$

$$\Phi : \boldsymbol{\lambda} \mapsto \left( \left( \alpha_{p,k} - \sum_{q=1}^Q |G_{qp}(k)|^2 p_q^*(k; \boldsymbol{\lambda}) \right)_{k=1}^N \right)_{p=1}^P \quad (1)$$

where  $\mathbf{p}^*(\boldsymbol{\lambda}) = \left( (p_q^*(k; \boldsymbol{\lambda}))_{k=1}^N \right)_{q=1}^Q$  is a Nash equilibrium of  $\mathcal{G}_{\boldsymbol{\lambda}}$  for a given  $\boldsymbol{\lambda} = \left( (\lambda_{p,k})_{k=1}^N \right)_{p=1}^P$ .

- **Theorem 2 (Existence and Uniqueness of the NE of  $\mathcal{G}$ ):**

- *The VI( $\mathcal{K}, \mathbf{F}$ ) always admits a solution  $\mathbf{p}^{\text{VI}}$  (the NE of  $\mathcal{G}$ )*

- *If  $\Upsilon \succ \mathbf{0}$  then*

- \*  *$\mathbf{p}^{\text{VI}}$  is unique and  $\mathcal{G}$  is equivalent to the NCP in the price  $\lambda$*

$$\text{NCP}(\Phi) : \quad 0 \leq \lambda \perp \Phi(\lambda) \geq 0$$

- \* *the game  $\mathcal{G}$  has a unique least-norm price tuple  $\lambda^{\text{NE,lm}}$ .*

- The uniqueness is only in the powers but not in the prices. However, under  $\Upsilon \succ \mathbf{0}$ , *all* the optimal prices (=solutions to NCP) yield the same *unique* optimal powers  $\mathbf{p}^{\text{VI}}$ .

- The NCP reformulation is instrumental to devise distributed algorithms.

# Distributed Algorithms based on VI

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## Algorithm 1: Projection algorithm with constant step-size

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- (S.0) : Choose any  $\lambda^{(0)} \geq \mathbf{0}$ , and the step size  $\tau > 0$ , and set  $n = 0$
- (S.1) : If  $\lambda^{(n)}$  satisfies a suitable termination criterion: STOP
- (S.2) : Given  $\lambda^{(n)}$ , compute  $\mathbf{p}^*(\lambda^{(n)})$  as the NE solution of the NEP  $\mathcal{G}_\lambda$  with *fixed* prices  $\lambda = \lambda^{(n)}$
- (S.3) : Update the price vectors:

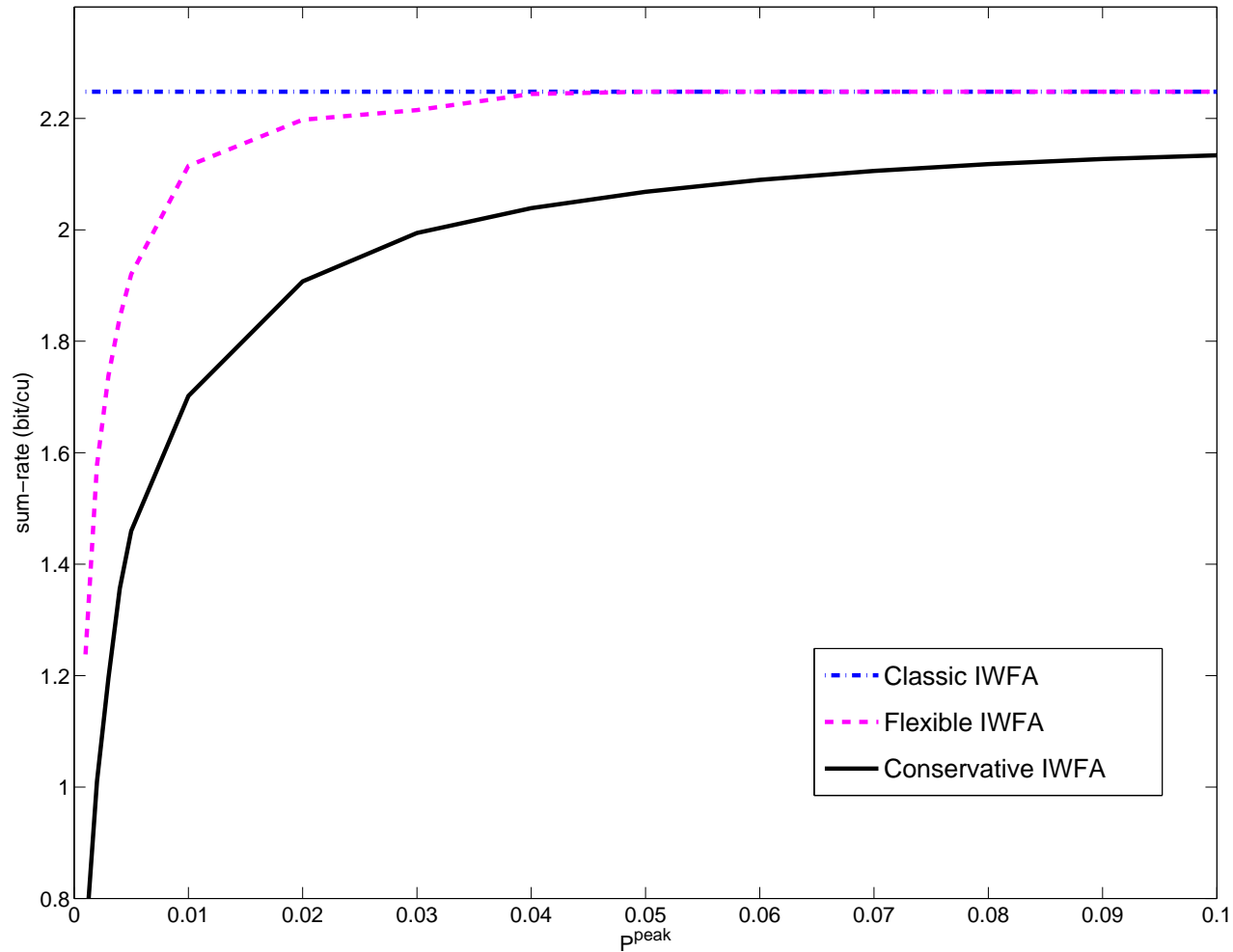
$$\lambda^{(n+1)} = \left[ \lambda^{(n)} - \tau \Phi \left( \lambda^{(n)} \right) \right]^+ \quad (2)$$

- (S.4) : Set  $n \leftarrow n + 1$ ; go to (S.1)
-

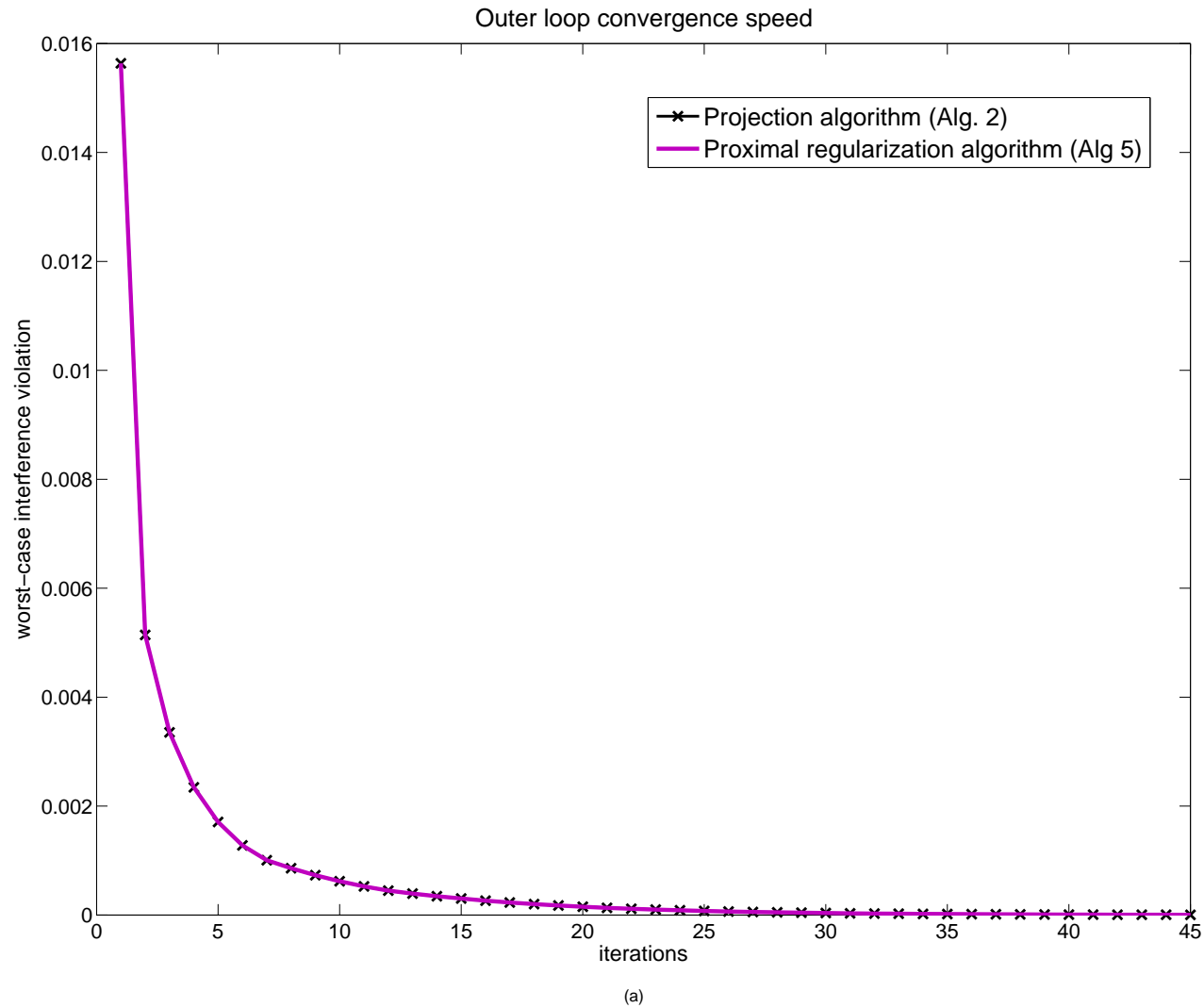
- The NE  $\mathbf{p}^*(\boldsymbol{\lambda}^{(n)})$  of  $\mathcal{G}_{\boldsymbol{\lambda}^{(n)}}$  can be computed using the asynchronous IWFA (convergence is guaranteed under  $\Upsilon \succ \mathbf{0}$ ).
- Distributed implementation: at the iteration  $n$ , the PUs measure the interference violation  $\Phi(\boldsymbol{\lambda}^{(n)})$ , update the prices  $\boldsymbol{\lambda}^{(n+1)}$  via the projection (2), and broadcast  $\boldsymbol{\lambda}^{(n+1)}$  to the SUs who play the game  $\mathcal{G}_{\boldsymbol{\lambda}^{(n+1)}}$  (asynchronous IWFA).
- **Theorem 3 (Global convergence):** *Suppose  $\Upsilon \succ \mathbf{0}$ . If the step-size  $\tau$  is sufficiently small, then the sequence  $\{\boldsymbol{\lambda}^{(n)}\}_{n=0}^{\infty}$  generated by Algorithm 1 converges to a solution of the NCP( $\Phi$ ).*
- Several other algorithms have been considered that differ in the trade-off between SUs/PUs signaling, computational complexity, convergence conditions.

# Numerical Results

# Achieved Sum-Rate

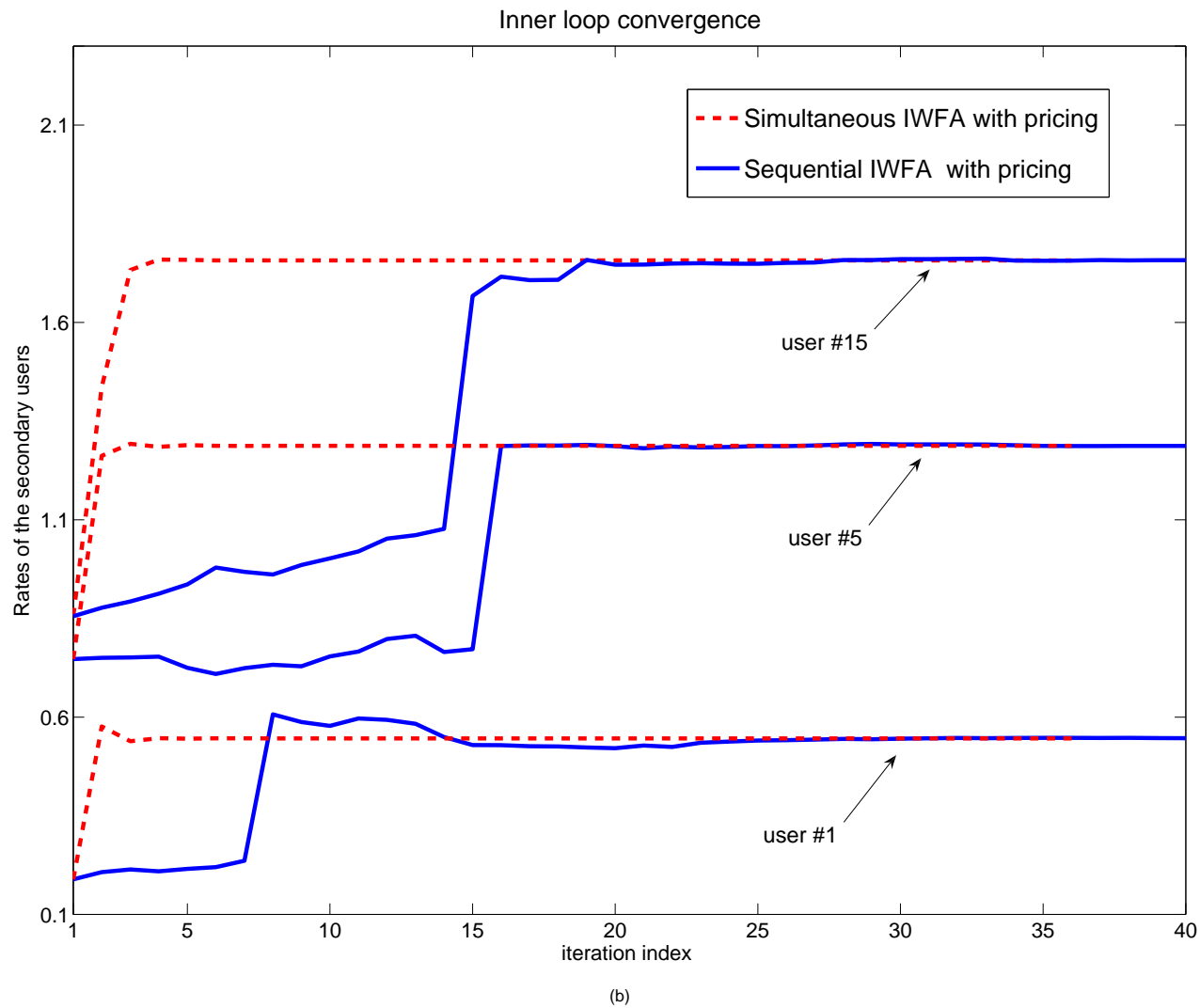


# Convergence of Outer Loop





# Convergence of Inner Loop



# Summary

- We have considered different game formulations of relevant wireless networks, starting from simple ad-hoc networks and building up to more complicated cognitive radio systems with temperature-interference constraints.
- The proper way to deal with temperature-interference constraints involves a coupling constraint in the game.
- Variational Inequality theory is a perfect mathematical framework for the analysis and design of such coupled games, both in theory and practice.

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# End of Talk

## Thank you !!

For more information visit:

<http://www.ece.ust.hk/~palomar>

## Deleted Parts

- The  $Q \times Q$  Z-matrix  $\Upsilon$

$$[\Upsilon]_{qr} \triangleq \begin{cases} 1 & \text{if } q = r \\ - \max_{1 \leq k \leq N} \left\{ \frac{|H_{qr}(k)|^2}{|H_{rr}(k)|^2} \cdot \text{innr}_{qr}(k) \right\} & \text{if } q \neq r, \end{cases} \quad (3)$$

with

$$\text{innr}_{qr}(k) \triangleq \frac{\sigma_r^2(k) + \sum_{r'} |H_{rr'}(k)|^2 p_{r'}^{\max}(k)}{\sigma_q^2(k)}$$